Last name	Name	student ID No.:

PC No. _____

Section 4: STABILITY OF LINEAR DYNAMIC SYSTEMS

A linear dynamic process has the following transfer functions:

$$G_2(s) = \frac{(s+1)}{\left(s-2\cdot\left(\frac{n-0.05}{n+0.05}\right)\right)} e^{-4\cdot\left(\frac{n-0.05}{n+0.05}\right)s}$$

where:

n = N. matricola (student ID No.)

- I. Is G₂(s) a BIBO stable system at **open-loop**?
- II. How much is the **gain**?
- III. Is G₂(s) an **inverse-response system**?

Part A: Root locus

For the open loop TF $G_2(s)$, answer the following questions aimed at focusing the Padé approximation:

- A1.Use a 1st order Padé approximation, plot the *root locus* by means of Matlab or SisoTool resources and attach it here
- A2.Calculate the limiting value/values K1*, if any
- A3.Use a 2nd order Padé approximation, plot the *root locus* by means of Matlab or SisoTool resources and attach it here
- A4.Calculate the limiting value/values K2*, if any
- A5.Use a 3rd order Padé approximation, plot the *root locus* by means of Matlab or SisoTool resources and attach it here

A6.Calculate the limiting value/values K_{3*}, if any

A7.By comparing all of the above results for the root locus, provide a short and reasoned comment

Part B: Frequency response

For the open loop TF G₂(s) and $\mathcal{K}c=1$, answer the following questions:

- B1)Use a 1st order Padé approximation, plot the **Bode Diagrams** by means of Matlab or SisoTool resources, with a *log scale of the magnitude (NOT in dB)*, and attach them here
- B2)Use a 2nd order Padé approximation, plot the **Bode Diagrams** by means of Matlab or SisoTool resources, with a *log scale of the magnitude (NOT in dB)*, and attach them here
- B3) Use a 3rd order Padé approximation, plot the **Bode Diagrams** by means of Matlab or SisoTool resources, with a *log scale of the magnitude (NOT in dB)*, and attach them here
- B4)Come back to the original TF G₂(s), plot the **Bode Diagrams** by means of Matlab resources, with a *log scale of the magnitude* (NOT in dB), and attach them here
- B5)Calculate the value of each TF in both **polar coordinates** (AR, ϕ) and **cartesian coordinates complex number** (a + jb) just corresponding to a given $\omega = 100$ rad/s, for all of the above four cases above
- B6)By comparing all of the above results for the **Bode Diagrams**, provide a short and reasoned comment
- B7)Use a 1st order Padé approximation, plot the **extended Nyquist Diagram** by means of Matlab or SisoTool resources, *together with the unit circle and the Peak Response*, and attach it here
- B8)Is the above **Nyquist diagram** crossing the **critical point**?
- B9) Check, on the base of the **Nyquist stability criterion**, if the above system is closed-loop stable

- B10) Come back to the original TF G₂(s), plot the **extended Nyquist Diagram** by means of Matlab or SisoTool resources, *together with the unit circle and the Peak Response*, and attach it here
- B11) By comparing the above two Nyquist Diagrams, provide a short and reasoned comment

Part C: Dynamic responses in the time domain

= = =

Part D:

= = =